

Due Today

### 3.2 – Norm, Dot Product, and Distance in $R^n$

Definition 1: If  $\mathbf{v} = (v_1, v_2, \dots, v_n)$  is a vector in  $R^n$ , then the **norm** of  $\mathbf{v}$  (also called its **length** or **magnitude**) is denoted by  $\|\mathbf{v}\|$  [by this author], and is defined by the formula

$$\|\mathbf{v}\| = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$$

**Theorem 3.2.1** Properties of the norm of a vector

If  $\mathbf{v}$  is a vector in  $R^n$  and  $k$  is any scalar, then:

a)  $\|\mathbf{v}\| \geq 0$

b)  $\|\mathbf{v}\| = 0$  if and only if  $\mathbf{v} = \mathbf{0}$

c)  $\|k\mathbf{v}\| = |k|\|\mathbf{v}\|$

good to prove

The norm of a **unit vector** is 1.

$$\left\| \left( \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}} \right) \right\| = \sqrt{\frac{1}{3} + \frac{1}{3} + \frac{1}{3}} = 1$$

We can obtain a unit vector from a nonzero vector  $\mathbf{v}$  by multiplying by the reciprocal of its length. This process is called **normalizing** the vector.

1. Find the norm of  $\mathbf{v}$ , and a unit vector that is oppositely directed to  $\mathbf{v}$ .

a.  $\mathbf{v} = (2, 2, 2)$

b.  $\mathbf{v} = (1, 0, 2, 1, 3)$

$$b. \|\vec{v}\| = \sqrt{1^2 + 2^2 + 1^2 + 3^2} = \sqrt{15}$$

$$-\frac{1}{\|\vec{v}\|} \vec{v} = \left( -\frac{1}{\sqrt{15}}, 0, -\frac{2}{\sqrt{15}}, -\frac{1}{\sqrt{15}}, -\frac{3}{\sqrt{15}} \right)$$

$$(2, -3, 4) = 2\vec{e}_1 - 3\vec{e}_2 + 4\vec{e}_3 = 2(1, 0, 0) - 3(0, 1, 0) + 4(0, 0, 1)$$

The **standard unit vectors in  $\mathbb{R}^n$**  are the standard basis vectors for  $\mathbb{R}^n$ ,  $\mathbf{e}_1 = (1, 0, 0, \dots, 0)$ ,  $\mathbf{e}_2 = (0, 1, 0, \dots, 0)$ , ...,  $\mathbf{e}_n = (0, 0, 0, \dots, 1)$ .

Every vector in  $\mathbb{R}^n$  can be expressed as a linear combination of the standard basis vectors:

$$\vec{v} = v_1\vec{e}_1 + v_2\vec{e}_2 + \dots + v_n\vec{e}_n$$

Definition 2: If  $\mathbf{u} = (u_1, u_2, \dots, u_n)$  and  $\mathbf{v} = (v_1, v_2, \dots, v_n)$  are points in  $\mathbb{R}^n$ , then we denote the **distance** between  $\mathbf{u}$  and  $\mathbf{v}$  by  $d(\mathbf{u}, \mathbf{v})$  and define it to be

$$d(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\| = \sqrt{(u_1 - v_1)^2 + (u_2 - v_2)^2 + \dots + (u_n - v_n)^2}$$

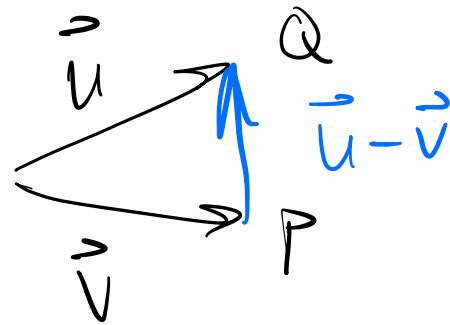
4. Evaluate the given expression with  $\mathbf{u} = (2, -2, 3)$ ,  $\mathbf{v} = (1, -3, 4)$ , and  $\mathbf{w} = (3, 6, -4)$ .

a.  $\|\mathbf{u} + \mathbf{v} + \mathbf{w}\|$

b.  $\|\mathbf{u} - \mathbf{v}\| \leftarrow \text{distance}$

c.  $\|3\mathbf{v}\| - 3\|\mathbf{v}\| = 0$

d.  $\|\mathbf{u}\| - \|\mathbf{v}\|$



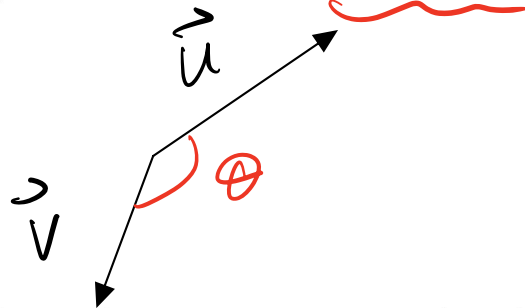
b.  $\vec{u} - \vec{v} = (2-1, -2+3, 3-4) = (1, 1, -1)$

$$\|\vec{u} - \vec{v}\| = \sqrt{3}$$

d.  $\|\vec{u}\| = \sqrt{4+4+9} = \sqrt{17}$ ,  $\|\vec{v}\| = \sqrt{1+9+16} = \sqrt{26}$

$$\|\vec{u}\| - \|\vec{v}\| = \sqrt{17} - \sqrt{26}$$

Let  $\mathbf{u}$  and  $\mathbf{v}$  be nonzero vectors in  $R^n$  positioned so that their initial points coincide. The **angle between  $\mathbf{u}$  and  $\mathbf{v}$**  is the angle  $\theta$  determined by  $\mathbf{u}$  and  $\mathbf{v}$  such that  $0 \leq \theta \leq \pi$ .



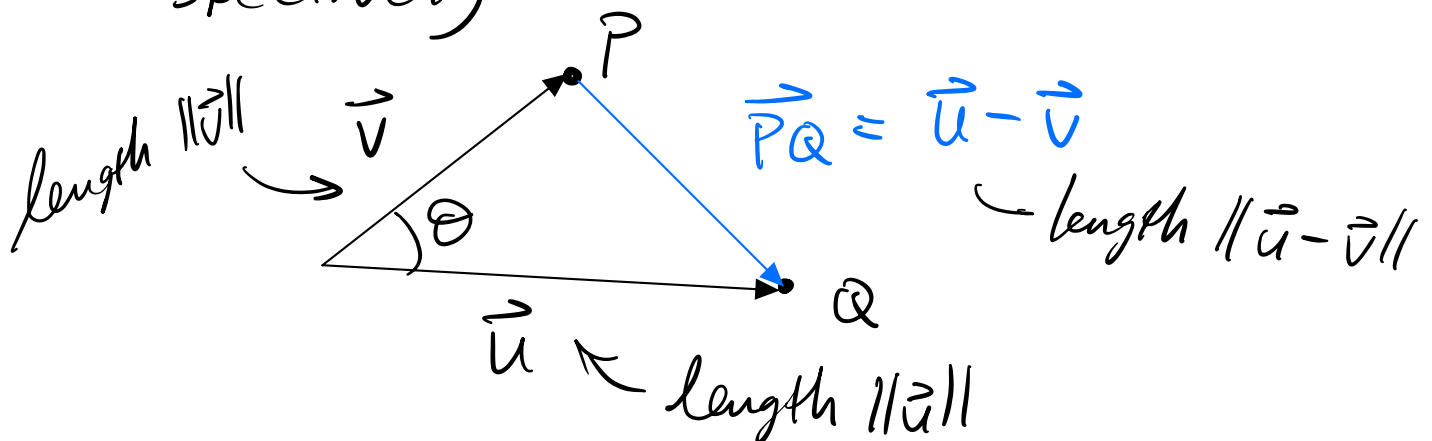
Definition 3: If  $\mathbf{u}$  and  $\mathbf{v}$  are nonzero vectors in  $R^2$  or  $R^3$ , and if  $\theta$  is the angle between  $\mathbf{u}$  and  $\mathbf{v}$ , then the **dot product** or **Euclidean inner product** of  $\mathbf{u}$  and  $\mathbf{v}$  is denoted by  $\mathbf{u} \cdot \mathbf{v}$  and is defined as  $\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos \theta$ . If  $\mathbf{u} = \mathbf{0}$  or  $\mathbf{v} = \mathbf{0}$ , then we define  $\mathbf{u} \cdot \mathbf{v}$  to be 0.  *$\vec{u} \vec{v}$  is not a thing*

Definition 4: If  $\mathbf{u} = (u_1, u_2, \dots, u_n)$  and  $\mathbf{v} = (v_1, v_2, \dots, v_n)$  are vectors in  $R^n$ , then the **dot product** or **Euclidean inner product** of  $\mathbf{u}$  and  $\mathbf{v}$  is denoted by  $\mathbf{u} \cdot \mathbf{v}$  and is defined by

$$\mathbf{u} \cdot \mathbf{v} = u_1 v_1 + u_2 v_2 + \dots + u_n v_n.$$

To connect these two definitions,

let  $\vec{u}$  &  $\vec{v}$  share an initial point in  $R^3$  and let  $Q$  &  $P$  be their terminal points, respectively



By the Law of Cosines,

$$\|\vec{u} - \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2 - 2\|\vec{u}\|\|\vec{v}\|\cos\theta$$

$$\begin{aligned}\Rightarrow \|\vec{u}\|\|\vec{v}\|\cos\theta &= \frac{1}{2}(\|\vec{u}\|^2 + \|\vec{v}\|^2 - \|\vec{u} - \vec{v}\|^2) \\ &= \frac{1}{2}(u_1^2 + u_2^2 + u_3^2 + v_1^2 + v_2^2 + v_3^2 \\ &\quad - (u_1 - v_1)^2 - (u_2 - v_2)^2 - (u_3 - v_3)^2)\end{aligned}$$

$$\|\vec{u}\|\|\vec{v}\|\cos\theta = u_1v_1 + u_2v_2 + u_3v_3 = \vec{u} \cdot \vec{v}$$

In general,  $\vec{u} \cdot \vec{v} = u_1v_1 + u_2v_2 + \dots + u_nv_n$

10. Find  $\mathbf{u} \cdot \mathbf{v}$ ,  $\mathbf{u} \cdot \mathbf{u}$ , and  $\mathbf{v} \cdot \mathbf{v}$ .

a.  $\mathbf{u} = (1, 1, -2, 3)$ ,  $\mathbf{v} = (-1, 0, 5, 1)$

b.  $\mathbf{u} = (2, -1, 1, 0, -2)$ ,  $\mathbf{v} = (1, 2, 2, 2, 1)$

b.  $\vec{u} \cdot \vec{v} = 2(1) + (-1)(2) + 1(2) + 0(2) + (-2)(1)$   
 $= 0 = \|\vec{u}\|\|\vec{v}\|\cos\theta \Rightarrow \theta = \frac{\pi}{2}$

$$\vec{u} \cdot \vec{u} = 2^2 + (-1)^2 + 1^2 + 0^2 + (-2)^2 = 10 \leftarrow \|\vec{u}\|^2$$

$$\vec{v} \cdot \vec{v} = 1^2 + 2^2 + 2^2 + 2^2 + 1^2 = 14 \leftarrow \|\vec{v}\|^2$$

11. Find the Euclidean distance between  $\mathbf{u}$  and  $\mathbf{v}$  and the cosine of the angle between those vectors. State whether that angle is acute, obtuse, or  $90^\circ$

a.  $\mathbf{u} = (3, 3, 3), \mathbf{v} = (1, 0, 4)$

b.  $\mathbf{u} = (0, -2, -1, 1), \mathbf{v} = (-3, 2, 4, 4)$

$$a) d(\vec{u}, \vec{v}) = \sqrt{(3-1)^2 + (3-0)^2 + (3-4)^2} = \sqrt{14}$$

$$\cos \theta = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} = \frac{15}{3\sqrt{3} \sqrt{17}} = \frac{15}{3\sqrt{51}}$$

Since  $\cos \theta > 0$ ,  $0 < \theta < \frac{\pi}{2}$  (acute).

b)  $\vec{u} \cdot \vec{v} < 0 \Rightarrow \theta$  is obtuse.

### Theorem 3.2.2 Properties of the dot product

If  $\mathbf{u}, \mathbf{v}$ , and  $\mathbf{w}$  are vectors in  $R^n$  and if  $k$  is a scalar, then:

- a)  $\mathbf{u} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{u}$  (symmetry property)
- b)  $\mathbf{u} \cdot (\mathbf{v} + \mathbf{w}) = \mathbf{u} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{w}$  (distributive property)
- c)  $k(\mathbf{u} \cdot \mathbf{v}) = (k\mathbf{u}) \cdot \mathbf{v}$  (homogeneity property)
- d)  $\mathbf{v} \cdot \mathbf{v} \geq 0$  and  $\mathbf{v} \cdot \mathbf{v} = 0$  if and only if  $\mathbf{v} = \mathbf{0}$  (positivity property)

Pr: b) Let  $\vec{u} = (u_1, u_2, \dots, u_n)$ ,  $\vec{v} = (v_1, v_2, \dots, v_n)$ ,  
 $\vec{w} = (w_1, w_2, \dots, w_n)$

Then  $\vec{u} \cdot (\vec{v} + \vec{w}) = (u_1, u_2, \dots, u_n) \cdot (v_1 + w_1, v_2 + w_2, \dots, v_n + w_n)$   
 (def of vector addition)  
 $= u_1(v_1 + w_1) + u_2(v_2 + w_2) + \dots + u_n(v_n + w_n)$   
 (def of dot product)  
 $= u_1v_1 + u_1w_1 + u_2v_2 + u_2w_2 + \dots + u_nv_n + u_nw_n$   
 (dist. prop of mult. of real #s)  
 $= u_1v_1 + u_2v_2 + \dots + u_nv_n + u_1w_1 + u_2w_2 + \dots + u_nw_n$   
 (comm. prop. of add. of real #s)  
 $= \vec{u} \cdot \vec{v} + \vec{u} \cdot \vec{w}$   
 (def of dot product) ✓

**Theorem 3.2.3** More properties of the dot product

If  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  are vectors in  $R^n$  and if  $k$  is a scalar, then:

- a)  $\mathbf{0} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{0} = 0$
- b)  $(\mathbf{u} + \mathbf{v}) \cdot \mathbf{w} = \mathbf{u} \cdot \mathbf{w} + \mathbf{v} \cdot \mathbf{w}$
- c)  $\mathbf{u} \cdot (\mathbf{v} - \mathbf{w}) = \mathbf{u} \cdot \mathbf{v} - \mathbf{u} \cdot \mathbf{w}$
- d)  $(\mathbf{u} - \mathbf{v}) \cdot \mathbf{w} = \mathbf{u} \cdot \mathbf{w} - \mathbf{v} \cdot \mathbf{w}$
- e)  $k(\mathbf{u} \cdot \mathbf{v}) = \mathbf{u} \cdot (k\mathbf{v})$

*- a necessary result for the def of dot product*  
**Theorem 3.2.4** Cauchy-Schwarz Inequality

If  $\mathbf{u} = (u_1, u_2, \dots, u_n)$  and  $\mathbf{v} = (v_1, v_2, \dots, v_n)$  are vectors in  $R^n$ , then

$|\mathbf{u} \cdot \mathbf{v}| \leq \|\mathbf{u}\| \|\mathbf{v}\|$  or in terms of components

$$|u_1 v_1 + u_2 v_2 + \dots + u_n v_n| \leq (u_1^2 + u_2^2 + \dots + u_n^2)^{1/2} (v_1^2 + v_2^2 + \dots + v_n^2)^{1/2}$$

**Theorem 3.2.5** Triangle Inequalities

If  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  are vectors in  $R^n$ , then:

- a)  $\|\mathbf{u} + \mathbf{v}\| \leq \|\mathbf{u}\| + \|\mathbf{v}\|$  (triangle inequality for vectors)
- b)  $d(\mathbf{u}, \mathbf{v}) \leq d(\mathbf{u}, \mathbf{w}) + d(\mathbf{w}, \mathbf{v})$  (triangle inequality for distances)

Pf: a)  $\|\vec{u} + \vec{v}\|^2 = (\vec{u} + \vec{v}) \cdot (\vec{u} + \vec{v}) = \underline{\vec{u} \cdot \vec{u}} + \underline{2\vec{u} \cdot \vec{v}} + \underline{\vec{v} \cdot \vec{v}}$

$$\leq \underline{\|\vec{u}\|^2} + \underline{2|\vec{u} \cdot \vec{v}|} + \underline{\|\vec{v}\|^2}$$

(prop. of abs. value)

$$\leq \|\vec{u}\|^2 + \underline{2\|\vec{u}\|\|\vec{v}\|} + \|\vec{v}\|^2$$

(Cauchy-Schwarz inequality)

$$= (\|\vec{u}\| + \|\vec{v}\|)^2$$

Taking square roots yields  $\|\vec{u} + \vec{v}\| \leq \|\vec{u}\| + \|\vec{v}\|$ .

b) follows from (a) and Def. 2.

Note: An expression like  $\vec{u} \cdot \vec{v} \cdot \vec{w}$  has no meaning. But we can consider matrix mult. using the dot product:

If  $A$  is an  $n \times n$  matrix and  $\vec{u}$  &  $\vec{v}$  are  $n \times 1$  matrices (columns), then

$$A \vec{u} \cdot \vec{v} = \vec{v}^T (A \vec{u}) = (\vec{v}^T A) \vec{u} = (A^T \vec{v})^T \vec{u} = \vec{u} \cdot A^T \vec{v}$$

$\begin{matrix} n \times n & n \times 1 \\ n \times 1 & n \times 1 \end{matrix}$ 
 $\begin{matrix} 1 \times n & n \times 1 \end{matrix}$ 
 $\begin{matrix} 1 \times n & n \times n \\ 1 \times n & n \times 1 \end{matrix}$ 
 $\begin{matrix} n \times n & n \times 1 & n \times 1 \\ n \times 1 & & n \times 1 \end{matrix}$

So  $A \vec{u} \cdot \vec{v} = \vec{u} \cdot A^T \vec{v}$ . Likewise,  
 $\vec{u} \cdot A \vec{v} = A^T \vec{u} \cdot \vec{v}$ .

Last note: If we represent  $A$  ( $m \times n$ ) and

$$B$$
 ( $n \times r$ ) as  $A = \begin{bmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_m \end{bmatrix}$  and  $B = [\vec{c}_1 \ \vec{c}_2 \ \dots \ \vec{c}_r]$

then

$$AB = \begin{bmatrix} \vec{r}_1 \cdot \vec{c}_1 & \vec{r}_1 \cdot \vec{c}_2 & \dots & \vec{r}_1 \cdot \vec{c}_r \\ \vdots & \vdots & & \vdots \\ \vec{r}_m \cdot \vec{c}_1 & \vec{r}_m \cdot \vec{c}_2 & \dots & \vec{r}_m \cdot \vec{c}_r \end{bmatrix}$$